Fichier Édition Croquis Outils Aide

Marlin | BlinkM.cpp | BlinkM.h | Configuration.h | ConfigurationStore.cpp | ConfigurationStore.h | Configuration_adv.h | DOGMbitmaps.h | LiquidCrystalRus.cpp

```
  digitalWrite(en_pin , HIGH); //disable motor
}

//ALL STEPPER ROTATION
// in the same time, good for debug
//  dir     = which direction you go
//  steps   = number of step to perform
//  (temp   = delay between steps : default = 10ms)
void rotate_all(boolean dir,int steps,int temp = 10) {

  //INIT ALL
  for(int i = 0; i< 5 ; i++){
    digitalWrite(en_all[i] , LOW); //default ENABLE LOW because stepper driver use "not enable" input
    digitalWrite(dir_all[i],dir);  //set dir
  }
  //ROTATE ALL
  for(int a=0; a <steps;a++) {
    for(int i=0; i <5;i++) {
      delayMicroseconds(temp);
      digitalWrite(step_all[i], LOW);
      delayMicroseconds(temp);
      digitalWrite(step_all[i], HIGH);
    }

  }
```

'Serial' was not declared in this scope

Recopier les messages d'erreur

```
debug_Ramps.ino: In function 'void setup()':
debug_Ramps:287: error: 'Serial' was not declared in this scope
debug_Ramps.ino: In function 'void loop()':
debug_Ramps:356: error: 'Serial' was not declared in this scope
'Serial' was not declared in this scope
```

119 - 140   Arduino Mega or Mega 2560, ATmega2560 (Mega 2560) on COM9