

Send: G28

== Er fährt hoch nach home

Recv: T:18.57 /0.00 B:18.71 /0.00 @:0 B@:0

Recv: echo:busy: processing

Printer seems to support the busy protocol, will adjust timeouts and set busy interval accordingly

Recv: T:18.57 /0.00 B:18.67 /0.00 @:0 B@:0

Recv: echo:busy: processing

Recv: X:200.00 Y:200.00 Z:193.00 E:0.00 Count X:16000 Y:16000 Z:617600

Recv: ok

Send: M113 S2

Recv: ok

Recv: T:18.57 /0.00 B:18.63 /0.00 @:0 B@:0

Recv: T:18.57 /0.00 B:18.44 /0.00 @:0 B@:0

Send: G1 Z0

== er fährt runter bis kurz vor das Heizbett

Recv: ok

Send: G29

== er fängt an zu „tasten“ / aber ganz komisch, und immer höher

Recv: echo:busy: processing

Recv: Bilinear Leveling Grid:

Recv: 0 1 2

Recv: 0 +9.999 +19.999 +29.998

Recv: 1 +59.996 +49.997 +39.998

Recv: 2 +69.996 +79.995 +89.994

Recv:

Recv: X:193.00 Y:180.00 Z:5.60 E:0.00 Count X:15440 Y:14400 Z:305902

Recv: ok

Recv: echo:endstops hit: P:90.59